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$x + b + jx + bj. + k = \ln. x + b + (x + b) + k = \ln(2(x + b)) + k = \ln(x + b) + \ln 2 + k$ Thus our earlier formula works in the case that $b^2 = c$ and $x + b > 0$, where we take $k_0 = k + \ln 2$ (which we may do, as they are arbitrary constants).

Next, when $x + b < 0$, direct integration yields: $\int \frac{1}{x^2 + 2bx + b} dx = \int \frac{1}{jx + bj} dx = Z.$

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The solutions of this quadratic are given by $x = \frac{-1 \pm \sqrt{1 + 4a^2}}{2}$; and these will be real solutions of if and only if $x > 0$ and $a > 0$, that is $0 < x < a$. But as $2x = x$, we will always have a $x > 0$ for real solutions of the quadratic, so we need only check that $x > 0$. For a solution to $()$, we therefore require the plus sign in the

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First, draw a diagram: The position vector of point P is: $x \hat{i} + y \hat{j} = a \sin \theta \hat{i} + a(1 - \cos \theta) \hat{j} = a(\sin \theta) \hat{i} + a(1 - \cos \theta) \hat{j}$ and the velocity vector is: $\dot{x} \hat{i} + \dot{y} \hat{j} = a \dot{\theta} \cos \theta \hat{i} - a \dot{\theta} \sin \theta \hat{j} = a \dot{\theta}(\cos \theta \hat{i} - \sin \theta \hat{j})$ The speed is given by $v^2 = \dot{x}^2 + \dot{y}^2 = a^2 \dot{\theta}^2 (\cos^2 \theta + \sin^2 \theta) = a^2 \dot{\theta}^2$.

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Hints & Solutions for Paper 9470 (STEP II) June 2012 Question 1 To be honest, the binomial expansions of $(1 + x)^n$, in the cases $n = 1, 2$, are used so frequently within AS- and A-levels that they should be familiar to all candidates taking STEPs. Replacing x by x^k is no great further leap.

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