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IEEE Trans Neural Syst Rehabil
Eng. 2007 Sep;15 (3):387-400. A
robot and control algorithm that
can synchronously assist in
naturalistic motion during body-
weight-supported gait training
following neurologic injury. Aoyagi
D (1), Ichinose WE, Harkema SJ,
Reinkensmeyer DJ, Bobrow JE.

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Network-Based Approach to Robot
Motion Control Uli Grasmann,
Daniel Stronger, and Peter Stone
Department of Computer Sciences
University of Texas at Austin
Austin, TX 78712, USA {uli,stronger,
pstone}@cs.utexas.edu
Abstract.

A Neural Network-Based
Approach to Robot Motion Control
Abstract: Robot navigation in the
presence of humans raises new
issues for motion planning and
control when the humans must be
taken explicitly into account. We
claim that a human aware motion
planner (HAMP) must not only
provide safe robot paths, but also
synthesize good, socially
acceptable and legible paths.

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Abstract: This paper presents a motion control method for mobile robots in partially unknown environments populated with moving obstacles. The proposed method is based on the integration of focused D^* search algorithm and dynamic window local obstacle avoidance algorithm with some adaptations that provide efficient avoidance of moving obstacles.

Dynamic window based approach
to mobile robot motion ...
Motion control in automation is the

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process of moving an object in a controlled manner, this can take many forms from a simple linear actuator to complex robot cell. For the last two decades we have been helping business ' improve their process ' with the aid of motion control solutions.

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Robertz, Sven LU ; Nilsson, Klas
LU ; Henriksson, Roger LU and
Blomdell, Anders LU (2007) 12th
IEEE Conference on Emerging
Technologies and Factory
Automation p.1453-1456

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Robot control is the system that contributes to the movement of robots. This involves the mechanical aspects and program systems that makes possible to control robots. Robotics could be controlled in various ways, which includes using manual control, wireless control, semi-autonomous (which is a mix of fully automatic and wireless control), and fully autonomous (which is when it uses AI to ...

Robot control - Wikipedia
Ahmed R.M., Ananiev A.V.,
Kalaykov I.G. (2009) Compliant
Motion Control for Safe Human
Robot Interaction. In: Koz łowski
K.R. (eds) Robot Motion and
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