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solutions are $(C y=C x) = 1 2$ and $(C z=C x) = 1 2$, so that $C = C x(\hat{i} 1 2 \hat{j} + 1 2 \hat{k})$.

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Thus, $?12 3==??$, so that a unit vector in the direction of the axis of rotation is. $n= e e e()/312 3++$. Lai et al, Introduction to Continuum

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Mechanics. Copyright 2010, Elsevier Inc 2-9. 2.29 A rigid body undergoes a right hand rotation of angle θ about an axis which is in the direction of the unit vectorm.

CHAPTER 2, PART A

W. Michael Lai is Professor Emeritus of Mechanical Engineering and Orthopaedic Bioengineering at Columbia University. He received his Ph.D in Engineering Mechanics in 1962 from the University of Michigan.

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